

# NAG Toolbox for MATLAB

## f07nn

### 1 Purpose

f07nn computes the solution to a complex system of linear equations

$$AX = B,$$

where  $A$  is an  $n$  by  $n$  symmetric matrix and  $X$  and  $B$  are  $n$  by  $r$  matrices.

### 2 Syntax

```
[a, ipiv, b, info] = f07nn(uplo, a, b, 'n', n, 'nrhs_p', nrhs_p)
```

### 3 Description

f07nn uses the diagonal pivoting method to factor  $A$  as  $A = UDU^T$  if **uplo** = 'U' or  $A = LDL^T$  if **uplo** = 'L', where  $U$  (or  $L$ ) is a product of permutation and unit upper (lower) triangular matrices, and  $D$  is symmetric and block diagonal with 1 by 1 and 2 by 2 diagonal blocks. The factored form of  $A$  is then used to solve the system of equations  $AX = B$ .

### 4 References

Anderson E, Bai Z, Bischof C, Blackford S, Demmel J, Dongarra J J, Du Croz J J, Greenbaum A, Hammarling S, McKenney A and Sorensen D 1999 *LAPACK Users' Guide* (3rd Edition) SIAM, Philadelphia URL: <http://www.netlib.org/lapack/lug>

Golub G H and Van Loan C F 1996 *Matrix Computations* (3rd Edition) Johns Hopkins University Press, Baltimore

Higham N J 2002 *Accuracy and Stability of Numerical Algorithms* (2nd Edition) SIAM, Philadelphia

### 5 Parameters

#### 5.1 Compulsory Input Parameters

1: **uplo** – string

If **uplo** = 'U', the upper triangle of  $A$  is stored.

If **uplo** = 'L', the lower triangle of  $A$  is stored.

*Constraint:* **uplo** = 'U' or 'L'.

2: **a(lda,\*)** – complex array

The first dimension of the array **a** must be at least  $\max(1, \mathbf{n})$

The second dimension of the array must be at least  $\max(1, \mathbf{n})$

The  $n$  by  $n$  symmetric matrix  $A$ .

If **uplo** = 'U', the upper triangular part of  $A$  must be stored and the elements of the array below the diagonal are not referenced.

If **uplo** = 'L', the lower triangular part of  $A$  must be stored and the elements of the array above the diagonal are not referenced.

3: **b(lb,\*)** – complex array

The first dimension of the array **b** must be at least  $\max(1, \mathbf{n})$

The second dimension of the array must be at least  $\max(1, \mathbf{nrhs\_p})$

**Note:** To solve the equations  $Ax = b$ , where  $b$  is a single right-hand side,  $\mathbf{b}$  may be supplied as a one-dimensional array with length  $\mathbf{ldb} = \max(1, \mathbf{n})$ .

The  $n$  by  $r$  right-hand side matrix  $B$ .

## 5.2 Optional Input Parameters

### 1: $\mathbf{n}$ – int32 scalar

*Default:* The second dimension of the array  $\mathbf{a}$ .

$n$ , the number of linear equations, i.e., the order of the matrix  $A$ .

*Constraint:*  $\mathbf{n} \geq 0$ .

### 2: $\mathbf{nrhs\_p}$ – int32 scalar

*Default:* The second dimension of the array  $\mathbf{b}$ .

$r$ , the number of right-hand sides, i.e., the number of columns of the matrix  $B$ .

*Constraint:*  $\mathbf{nrhs\_p} \geq 0$ .

## 5.3 Input Parameters Omitted from the MATLAB Interface

$\mathbf{lda}$ ,  $\mathbf{ldb}$ ,  $\mathbf{work}$ ,  $\mathbf{lwork}$

## 5.4 Output Parameters

### 1: $\mathbf{a}(\mathbf{lda},*)$ – complex array

The first dimension of the array  $\mathbf{a}$  must be at least  $\max(1, \mathbf{n})$

The second dimension of the array must be at least  $\max(1, \mathbf{n})$

If  $\mathbf{info} = 0$ , the block diagonal matrix  $D$  and the multipliers used to obtain the factor  $U$  or  $L$  from the factorization  $\mathbf{a} = UDU^T$  or  $\mathbf{a} = LDL^T$  as computed by f07nr.

### 2: $\mathbf{ipiv}(*)$ – int32 array

**Note:** the dimension of the array  $\mathbf{ipiv}$  must be at least  $\max(1, \mathbf{n})$ .

Details of the interchanges and the block structure of  $D$ , as determined by f07nr.

$\mathbf{ipiv}(k) > 0$

Rows and columns  $k$  and  $\mathbf{ipiv}(k)$  were interchanged, and  $D(k, k)$  is a 1 by 1 diagonal block.

$\mathbf{uplo} = 'U'$  and  $\mathbf{ipiv}(k) = \mathbf{ipiv}(k - 1) < 0$

Rows and columns  $k - 1$  and  $-\mathbf{ipiv}(k)$  were interchanged and  $D(k - 1 : k, k - 1 : k)$  is a 2 by 2 diagonal block.

$\mathbf{uplo} = 'L'$  and  $\mathbf{ipiv}(k) = \mathbf{ipiv}(k + 1) < 0$

Rows and columns  $k + 1$  and  $-\mathbf{ipiv}(k)$  were interchanged and  $D(k : k + 1, k : k + 1)$  is a 2 by 2 diagonal block.

### 3: $\mathbf{b}(\mathbf{ldb},*)$ – complex array

The first dimension of the array  $\mathbf{b}$  must be at least  $\max(1, \mathbf{n})$

The second dimension of the array must be at least  $\max(1, \mathbf{nrhs\_p})$

**Note:** To solve the equations  $Ax = b$ , where  $b$  is a single right-hand side,  $\mathbf{b}$  may be supplied as a one-dimensional array with length  $\mathbf{ldb} = \max(1, \mathbf{n})$ .

If  $\mathbf{info} = 0$ , the  $n$  by  $r$  solution matrix  $X$ .

4: **info** – **int32 scalar**

**info** = 0 unless the function detects an error (see Section 6).

## 6 Error Indicators and Warnings

Errors or warnings detected by the function:

**info** =  $-i$

If **info** =  $-i$ , parameter  $i$  had an illegal value on entry. The parameters are numbered as follows:

1: **uplo**, 2: **n**, 3: **nrhs\_p**, 4: **a**, 5: **lda**, 6: **ipiv**, 7: **b**, 8: **ldb**, 9: **work**, 10: **lwork**, 11: **info**.

It is possible that **info** refers to a parameter that is omitted from the MATLAB interface. This usually indicates that an error in one of the other input parameters has caused an incorrect value to be inferred.

**info** > 0

If **info** =  $i$ ,  $d_{ii}$  is exactly zero. The factorization has been completed, but the block diagonal matrix  $D$  is exactly singular, so the solution could not be computed.

## 7 Accuracy

The computed solution for a single right-hand side,  $\hat{x}$ , satisfies an equation of the form

$$(A + E)\hat{x} = b,$$

where

$$\|E\|_1 = O(\epsilon)\|A\|_1$$

and  $\epsilon$  is the *machine precision*. An approximate error bound for the computed solution is given by

$$\frac{\|\hat{x} - x\|_1}{\|x\|_1} \leq \kappa(A) \frac{\|E\|_1}{\|A\|_1},$$

where  $\kappa(A) = \|A^{-1}\|_1 \|A\|_1$ , the condition number of  $A$  with respect to the solution of the linear equations. See Section 4.4 of Anderson *et al.* 1999 and Chapter 11 of Higham 2002 for further details.

f07np is a comprehensive LAPACK driver that returns forward and backward error bounds and an estimate of the condition number. Alternatively, f04dh solves  $Ax = b$  and returns a forward error bound and condition estimate. f04dh calls f07nn to solve the equations.

## 8 Further Comments

The total number of floating-point operations is approximately  $\frac{4}{3}n^3 + 8n^2r$ , where  $r$  is the number of right-hand sides.

The real analogue of this function is f07ma.

## 9 Example

```
uplo = 'Upper';
a = [complex(-0.56, +0.12), complex(-1.54, -2.86), complex(5.32, -1.59),
      complex(3.8, +0.92);
      complex(0, 0), complex(-2.83, -0.03), complex(-3.52, +0.58),
      complex(-7.86, -2.96);
      complex(0, 0), complex(0, 0), complex(8.86, +1.81), complex(5.14, -
      0.64);
      complex(0, 0), complex(0, 0), complex(0, 0), complex(-0.39, -0.71)];
b = [complex(-6.43, +19.24);
```

```

        complex(-0.49, -1.47);
        complex(-48.18, +66);
        complex(-55.64, +41.22)];
[aOut, ipiv, bOut, info] = f07nn(uplo, a, b)

aOut =
    -2.0954 - 2.2011i   -0.1071 - 0.3157i   -0.4823 + 0.0150i    0.4426 +
0.1936i
           0           4.4079 + 5.3991i   -0.6078 + 0.2811i    0.5279 -
0.3715i
           0           0           -2.8300 - 0.0300i   -7.8600 -
2.9600i
           0           0           0           -0.3900 -
0.7100i
ipiv =
           1
           2
          -2
          -2
bOut =
    -4.0000 + 3.0000i
     3.0000 - 2.0000i
    -2.0000 + 5.0000i
     1.0000 - 1.0000i
info =
           0

```

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